



NMEA Reference Manual

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NMEA Reference Manual

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About This Document

This document is intended for use only with SiRF Evaluation Kits. Some manufacturers of products containing SiRF GPS devices have the ability to add, remove, or change the structure and content of NMEA output messages and input messages within SiRF firmware. SiRF may also make such changes in specific applications or for specific customers. Such changes are not reflected in this document. Contact the manufacturer for support of those products.

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Preface



Most SiRF products support a subset of the NMEA-0183 standard for interfacing marine electronic devices as defined by the National Marine Electronics Association (NMEA).

The *NMEA Reference Manual* provides details of NMEA messages developed and defined by SiRF. It does not provide information about the complete NMEA-0183 interface standard.

Who Should Use This Guide

This manual was written assuming the user has a basic understanding of interface protocols and their use.

How This Guide Is Organized

This manual contains the following chapters:

Chapter 1, Output Messages defines NMEA standard output messages supported by SiRF and NMEA proprietary output messages developed by SiRF.

Chapter 2, Input Messages defines NMEA standard input messages supported by SiRF and NMEA proprietary input messages developed by SiRF.

Related Manuals

You can refer to the following document for more information:

- *NMEA-0183 Standard For Interfacing Marine Electronic Devices*
- *SiRF Binary Protocol Reference Manual*
- *SiRF Evaluation Kit User Guides*
- *SiRF System Development Kit User Guides*



General Format

NMEA 0183 messages use the ASCII character set and have a defined format. Each message begins with a \$ (hex 0x24) and end with a carriage return and line feed (hex 0x0D 0x0A, represented as <CR><LF>). Each message consists of one or more fields of ASCII letters and numbers, separated by commas. After the last field, and before the <CR><LF> is a checksum consisting of an asterisk (*, hex 0x2A) followed by two ASCII characters representing the hexadecimal value of the checksum. The checksum is computed as the exclusive OR of all characters between the \$ and * characters.

Note – In NMEA 0183 specifications earlier than version 2.3, the checksum is optional.

Note – All references to discontinued unsupported products GSW2 and SiRFXTac are provided for historical reasons only.

Output Messages



Table 1-1 lists each of the NMEA output messages specifically developed and defined by SiRF for use within SiRF products.

Table 1-1 NMEA Output Messages

| Message | Description |
|----------|--|
| GGA | Time, position and fix type data |
| GLL | Latitude, longitude, UTC time of position fix and status |
| GSA | GPS receiver operating mode, satellites used in the position solution, and DOP values |
| GSV | Number of GPS satellites in view satellite ID numbers, elevation, azimuth, & SNR values |
| MSS | Signal-to-noise ratio, signal strength, frequency, and bit rate from a radio-beacon receiver |
| RMC | Time, date, position, course and speed data |
| VTG | Course and speed information relative to the ground |
| ZDA | PPS timing message (synchronized to PPS) |
| 150 | OK to send message |
| 151 | GPS Data and Extended Ephemeris Mask |
| 152 | Extended Ephemeris Integrity |
| 154 | Extended Ephemeris ACK |
| 155 | Extended Ephemeris Proprietary Message |
| 156,0x20 | ECLM ACK/NACK |
| 156,0x21 | ECLM EE Get Age response |
| 156,0x22 | ECLM Get SGEE Age response |
| 156,0x23 | ECLM Download Initiate Request |
| 156,0x24 | ECLM Erase Storage File |
| 156,0x25 | ECLM Update File Content |
| 156,0x26 | ECLM Request File Content |
| 160 | Watchdog Timeout and Exception Condition |

A full description of the listed NMEA messages is provided in the following sections.

Table 1-2 summarizes which SiRF NMEA output messages are supported by the specific SiRF platforms.

Table 1-2 Supported NMEA Output Messages

| Message | GSW2 ¹ | SiRFDRIve ¹ | SiRFXTrac ¹ | SiRFLoc ¹ | GSW3 & GSWLT3 ¹ | SiRFDirect | GSD3tw | GSD3FLP | Code Linked Host | | GPIO Strapped Chip | | OSP NMEA Switch Msg | |
|----------|-------------------|------------------------|------------------------|----------------------|----------------------------|------------|--------|---------|------------------|-------|--------------------|-------|---------------------|-------|
| | | | | | | | | | GSD4t | GSD4e | GSD4t | GSD4e | GSD4t | GSD4e |
| GGA | All | All | All | All | All | All | All | All | All | All | No | All | No | All |
| GLL | All | All | All | All | All | All | All | All | All | All | No | All | No | All |
| GSA | All | All | All | All | All | All | All | All | All | All | No | All | No | All |
| GSV | All | All | All | All | All | All | All | All | All | All | No | All | No | All |
| MSS | All | No | No | No | No | No | No | No | No | No | No | No | No | No |
| RMC | All | All | All | All | All | All | All | All | All | All | No | All | No | All |
| VTG | All | All | All | All | All | All | All | All | No | No | No | All | No | All |
| ZDA | 2.3.2 and later | No | No | No | All | No | All | No | No | No | No | All | No | All |
| 150 | 2.3.2 and later | No | No | No | No | No | No | No | No | No | No | No | No | No |
| 151 | 2.5 and later | No | 2.3 and later | No | 3.2.0 and later | Yes | Yes | Yes | No | No | No | No | No | No |
| 152 | 2.5 and later | No | 2.3 and later | No | 3.2.0 and later | Yes | Yes | Yes | No | No | No | No | No | No |
| 154 | 2.5 and later | No | 2.3 and later | No | 3.2.0 and later | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 155 | No | No | No | No | No | No | No | Yes | No | No | No | No | No | No |
| 156,0x20 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 156,0x21 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 156,0x22 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 156,0x23 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 156,0x24 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 156,0x25 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 156,0x26 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 160 | No | No | No | No | No | No | No | No | No | Yes | No | Yes | No | Yes |

1. GSW2 and SiRFDRIve software only output NMEA version 2.20 (and earlier). Standard binaries for SiRFXTrac, GSW3, and GSWLT3 firmware use NMEA 3.0. Users of SiRF's software developer's kit can choose through software conditional defines (UI_NMEA_VERSION_XXX) to allow a choice between NMEA 2.20 and 3.00. The file NMEA_SIF.H contains the NMEA version defines.

In some numeric fields representing a single data element, leading zeros before a decimal are suppressed. A single "0" character preceding the decimal point is maintained. In compound numeric structures (such as LAT or LONG), leading zeros are suppressed only on the leftmost element. Trailing zeros are not suppressed.

Message ID GGA: Global Positioning System Fixed Data

Note – Fields marked in *italic red* apply only to NMEA version 2.3 (and later) in this NMEA message description.

Table 1-3 contains the values for the following example:

```
$GPGGA,002153.000,3342.6618,N,11751.3858,W,1,10,1.2,27.0,M,-34.2,M,,0000*5E<CR><LF>
```

Table 1-3 GGA Data Format

| Name | Example | Unit | Description |
|------------------------|------------|--------|---|
| Message ID | \$GPGGA | | GGA protocol header |
| UTC Time | 002153.000 | | hhmmss.sss |
| Latitude | 3342.6618 | | ddmm.mmmm |
| N/S Indicator | N | | N=north or S=south |
| Longitude | 11751.3858 | | dddmm.mmmm |
| E/W Indicator | W | | E=east or W=west |
| Position Fix Indicator | 1 | | See Table 1-4 |
| Satellites Used | 10 | | Range 0 to 12 |
| HDOP | 1.2 | | Horizontal Dilution of Precision |
| MSL Altitude | 27.0 | meters | |
| Units | M | meters | |
| Geoid Separation | -34.2 | meters | Geoid-to-ellipsoid separation. Ellipsoid altitude = MSL Altitude + Geoid Separation. |
| Units | M | meters | |
| Age of Diff. Corr. | | sec | Null fields when DGPS is not used |
| Diff. Ref. Station ID | 0000 | | |
| Checksum | *5E | | |
| <CR><LF> | | | End of message termination |

Table 1-4 Position Fix Indicator

| Value | Description |
|----------|---------------------------------------|
| 0 | Fix not available or invalid |
| 1 | GPS SPS Mode, fix valid |
| 2 | Differential GPS, SPS Mode, fix valid |
| 3-5 | Not supported |
| <i>6</i> | <i>Dead Reckoning Mode, fix valid</i> |

Note – A valid status is derived from all the parameters set in the software. This includes the minimum number of satellites required, any DOP mask setting, presence of DGPS corrections, etc. If the default or current software setting requires that a factor is met, then if that factor is not met the solution will be marked as invalid.

Message ID GLL: Geographic Position - Latitude/Longitude

Note – Fields marked in italic *red* apply only to NMEA version 2.3 (and later) in this NMEA message description.

Table 1-5 contains the values for the following example:

```
$GPGLL,3723.2475,N,12158.3416,W,161229.487,A,A*41<CR><LF>
```

Table 1-5 GLL Data Format

| Name | Example | Unit | Description |
|---------------|------------|------|---|
| Message ID | \$GPGLL | | GLL protocol header |
| Latitude | 3723.2475 | | ddmm.mmmm |
| N/S Indicator | N | | N=north or S=south |
| Longitude | 12158.3416 | | dddmm.mmmm |
| E/W Indicator | W | | E=east or W=west |
| UTC Time | 161229.487 | | hhmmss.sss |
| Status | A | | A=data valid or V=data not valid |
| <i>Mode</i> | <i>A</i> | | <i>A=Autonomous, D=DGPS, E=DR N = Output Data Not Valid R = Coarse Position¹</i> |
| Checksum | *41 | | |
| <CR><LF> | | | End of message termination |

1. Position was calculated based on one or more of the SVs having their states derived from almanac parameters, as opposed to ephemerides.

Message ID GSA: GNSS DOP and Active Satellites

Table 1-6 contains the values for the following example:

```
$GPGSA,A,3,07,02,26,27,09,04,15,, , , , ,1.8,1.0,1.5*33<CR><LF>
```

Table 1-6 GSA Data Format

| Name | Example | Unit | Description |
|-----------------------------|---------|------|----------------------------------|
| Message ID | \$GPGSA | | GSA protocol header |
| Mode 1 | A | | See Table 1-7 |
| Mode 2 | 3 | | See Table 1-8 |
| Satellite Used ¹ | 07 | | SV on Channel 1 |
| Satellite Used ¹ | 02 | | SV on Channel 2 |
| | | | |
| Satellite Used ¹ | | | SV on Channel 12 |
| PDOP ² | 1.8 | | Position Dilution of Precision |
| HDOP ² | 1.0 | | Horizontal Dilution of Precision |
| VDOP ² | 1.5 | | Vertical Dilution of Precision |
| Checksum | *33 | | |
| <CR><LF> | | | End of message termination |

1. Satellite used in solution.

2. Maximum DOP value reported is 50. When 50 is reported, the actual DOP may be much larger.

Table 1-7 Mode 1

| Value | Description |
|-------|--|
| M | Manual – Forced to operate in 2D or 3D mode |
| A | 2D Automatic – Allowed to automatically switch 2D/3D |

Table 1-8 Mode 2

| Value | Description |
|-------|-------------------|
| 1 | Fix not available |
| 2 | 2D (<4 SVs used) |
| 3 | 3D (>3 SVs used) |

Message ID GSV: GNSS Satellites in View

Table 1-9 contains the values for the following example:

```
$GPGSV,2,1,07,07,79,048,42,02,51,062,43,26,36,256,42,27,27,138,42*71
```

```
$GPGSV,2,2,07,09,23,313,42,04,19,159,41,15,12,041,42*41<CR><LF>
```

Table 1-9 GSV Data Format

| Name | Example | Unit | Description |
|---------------------------------|---------|---------|---|
| Message ID | \$GPGSV | | GSV protocol header |
| Number of Messages ¹ | 2 | | Total number of GSV messages to be sent in this group |
| Message Number ¹ | 1 | | Message number in this group of GSV messages |
| Satellites in View ¹ | 07 | | |
| Satellite ID | 07 | | Channel 1 (Range 1 to 32) |
| Elevation | 79 | degrees | Channel 1 (Maximum 90) |
| Azimuth | 048 | degrees | Channel 1 (True, Range 0 to 359) |
| SNR (C/N0) | 42 | dBHz | Range 0 to 99, null when not tracking |
| | | | |
| Satellite ID | 27 | | Channel 4 (Range 1 to 32) |
| Elevation | 27 | degrees | Channel 4 (Maximum 90) |
| Azimuth | 138 | degrees | Channel 4 (True, Range 0 to 359) |
| SNR (C/N0) | 42 | dBHz | Range 0 to 99, null when not tracking |
| Checksum | *71 | | |
| <CR><LF> | | | End of message termination |

1. Depending on the number of satellites tracked, multiple messages of GSV data may be required. In some software versions, the maximum number of satellites reported as visible is limited to 12, even though more may be visible.

Message ID MSS: MSK Receiver Signal

Note – Fields marked in italic *red* apply only to NMEA version 2.3 (and later) in this NMEA message description.

Table 1-10 contains the values for the following example:

```
$GPMSS,55,27,318.0,100,1,*57<CR><LF>
```

Table 1-10 MSS Data Format

| Name | Example | Unit | Description |
|-----------------------|----------|------|--|
| Message ID | \$GPMSS | | MSS protocol header |
| Signal Strength | 55 | dB | SS of tracked frequency |
| Signal-to-Noise Ratio | 27 | dB | SNR of tracked frequency |
| Beacon Frequency | 318.0 | kHz | Currently tracked frequency |
| Beacon Bit Rate | 100 | | bits per second |
| <i>Channel Number</i> | <i>1</i> | | <i>The channel of the beacon being used if a multi-channel beacon receiver is used</i> |
| Checksum | *57 | | |
| <CR><LF> | | | End of message termination |

Note – The MSS NMEA message can only be polled or scheduled using the MSK NMEA input message. See “Message ID MSK: MSK Receiver Interface” on page 2-17.

Message ID RMC: Recommended Minimum Specific GNSS Data

Note – Fields marked in *italic red* apply only to NMEA version 2.3 (and later) in this NMEA message description.

Table 1-11 contains the values for the following example:

```
$GPRMC,161229.487,A,3723.2475,N,12158.3416,W,0.13,309.62,120598,
,*10<CR><LF>
```

Table 1-11 RMC Data Format

| Name | Example | Unit | Description |
|----------------------------------|------------|---------|--|
| Message ID | \$GPRMC | | RMC protocol header |
| UTC Time | 161229.487 | | hhmmss.sss |
| Status ¹ | A | | A=data valid or V=data not valid |
| Latitude | 3723.2475 | | ddmm.mmmm |
| N/S Indicator | N | | N=north or S=south |
| Longitude | 12158.3416 | | dddmm.mmmm |
| E/W Indicator | W | | E=east or W=west |
| Speed Over Ground | 0.13 | knots | |
| Course Over Ground | 309.62 | degrees | True |
| Date | 120598 | | ddmmyy |
| Magnetic Variation ² | | degrees | E=east or W=west |
| East/West Indicator ² | E | | E=east |
| <i>Mode</i> | <i>A</i> | | <i>A=Autonomous, D=DGPS, E=DR, N = Output Data Not Valid R = Coarse Position³</i> |
| Checksum | *10 | | |
| <CR><LF> | | | End of message termination |

1. A valid status is derived from all the parameters set in the software. This includes the minimum number of satellites required, any DOP mask setting, presence of DGPS corrections, etc. If the default or current software setting requires that a factor is met, then if that factor is not met the solution will be marked as invalid.
2. SiRF Technology Inc. does not support magnetic declination. All “course over ground” data are geodetic WGS84 directions relative to true North.
3. Position was calculated based on one or more of the SVs having their states derived from almanac parameters, as opposed to ephemerides.

Message ID VTG: Course Over Ground and Ground Speed

Note – Fields marked in italic *red* apply only to NMEA version 2.3 (and later) in this NMEA message description.

Table 1-12 contains the values for the following example:

```
$GPVTG,309.62,T, ,M,0.13,N,0.2,K,A*23<CR><LF>
```

Table 1-12 VTG Data Format

| Name | Example | Unit | Description |
|-------------|----------|---------|--|
| Message ID | \$GPVTG | | VTG protocol header |
| Course | 309.62 | degrees | Measured heading |
| Reference | T | | True |
| Course | | degrees | Measured heading |
| Reference | M | | Magnetic ¹ |
| Speed | 0.13 | knots | Measured horizontal speed |
| Units | N | | Knots |
| Speed | 0.2 | km/hr | Measured horizontal speed |
| Units | K | | Kilometers per hour |
| <i>Mode</i> | <i>A</i> | | <i>A=Autonomous, D=DGPS, E=DR, N = Output Data Not Valid R = Coarse Position²</i> |
| Checksum | *23 | | |
| <CR><LF> | | | End of message termination |

1. SiRF Technology Inc. does not support magnetic declination. All “course over ground” data are geodetic WGS84 directions.
2. Position was calculated based on one or more of the SVs having their states derived from almanac parameters, as opposed to ephemerides.

Message ID ZDA: Time & Date

This message is included only with systems which support a time-mark output pulse identified as “1PPS”. Outputs the time associated with the current 1PPS pulse. Each message is output within a few hundred ms after the 1PPS pulse is output and tells the time of the pulse that just occurred.

Table 1-13 contains the values for the following example:

```
$GPZDA,181813,14,10,2003,,*4F<CR><LF>
```

Table 1-13 ZDA Data Format

| Name | Example | Unit | Description |
|---------------------------------|---------|--------|---|
| Message ID | \$GPZDA | | ZDA protocol header |
| UTC time | 181813 | hhmmss | The UTC time units are: hh = UTC hours from 00 to 23 mm = UTC minutes from 00 to 59 ss = UTC seconds from 00 to 59 Either using valid IONO/UTC or estimated from default leap seconds |
| Day | 14 | | Day of the month, range 1 to 31 |
| Month | 10 | | Month of the year, range 1 to 12 |
| Year | 2003 | | 1980 to 2079 |
| Local zone hour ¹ | | hour | Offset from UTC (set to 00) |
| Local zone minutes ¹ | | minute | Offset from UTC (set to 00) |
| Checksum | *4F | | |
| <CR><LF> | | | End of message termination |

1. Not supported by SiRF. Reported as 00.

Message ID 140: Proprietary

This message is reserved for SiRF extended ephemeris usage only. The content of this message is proprietary.

Table 1-14 contains the message parameter definitions.

Table 1-14 Proprietary

| Name | Example | Unit | Description |
|--------------------|-----------|------|----------------------------|
| Message ID | \$PSRF140 | | PSRF108 protocol header |
| Extended Ephemeris | | | Proprietary message |
| Checksum | | | |
| <CR><LF> | | | End of message termination |

Message ID 150: OkToSend

This message is sent out during power-saving modes such as TricklePower™ and Push-to-Fix™ to indicate when the receiver is ready to receive messages or when it is going into low-power mode. When power is restored, it is the first message sent, and when power is going to be reduced, it is the last message sent.

Table 1-15 contains the values for the following examples:

1. OkToSend

```
$PSRF150,1*3F<CR><LF>
```

2. not OkToSend

```
$PSRF150,0*3E<CR><LF>
```

Table 1-15 OkToSend Message Data Format

| Name | Example | Unit | Description |
|------------|-----------|------|--------------------------------|
| Message ID | \$PSRF150 | | PSRF150 protocol header |
| OkToSend | 1 | | 1=OK to send, 0=not OK to send |
| Checksum | *3F | | |
| <CR><LF> | | | End of message termination |

Message ID 151: GPS Data and Extended Ephemeris Mask

SiRFInstantFix uses Message ID 151 to request ephemerides for specific satellites.

```
$PSRF151,3,1485,147236.3,0x43002732*4A<CR><LF>
```

Table 1-16 contains the parameter definitions and example values.

Table 1-16 GPS Data and Ephemeris Mask

| Name | Example | Unit | Description |
|---------------------|------------|-------------|--|
| Message ID | \$PSRF151 | | PSRF151 protocol header |
| GPS_TIME_VALID_FLAG | 3 | N/A | Bit 0 = 1, GPS week is valid |
| GPS Week | 1485 | week number | Extended week number |
| GPS Time of Week | 147236.3 | seconds | GPS Time Of Week |
| EPH_REQ_MASK | 0x43002732 | N/A | Mask to indicate the satellites for which new ephemeris is needed. Eight characters preceded by the following characters, “0x”, are used to show this 32-bit mask (in hex). The MSB is for satellite PRN 32, and the LSB is for satellite PRN 1. |
| Checksum | | | |
| <CR><LF> | | | End of message termination |

Message ID 152: Extended Ephemeris Integrity

SiRFInstantFix uses Message ID 152 to report the validity of various aspects of satellite data in the receiver.

```
$PSRF152,0x43002712,0x43002712,0x00000001*44<CR><LF>
```

Table 1-17 contains the parameter definitions and example values.

Table 1-17 Extended Ephemeris Integrity

| Name | Example | Unit | Description |
|-----------------------|------------|------|---|
| Message ID | \$PSRF152 | | PSRF152 protocol header |
| SAT_POS_VALIDITY_FLAG | 0x00000002 | N/A | Hexadecimal representation of 32-bit field, where MSB represents satellite PRN 32, LSB satellite PRN 1. A bit set to 1 indicates an invalid position has been found for that satellite. |
| SAT_CLK_VALIDITY_FLAG | 0x00000002 | N/A | Hexadecimal representation of 32-bit field, where MSB represents satellite PRN 32, LSB satellite PRN 1. A bit set to 1 indicates that satellite has an invalid clock. |
| SAT_HEALTH_FLAG | 0x00000001 | N/A | Hexadecimal representation of 32-bit field, where MSB represents satellite PRN 32, LSB satellite PRN 1. A bit set to 1 indicates that satellite is reported to be unhealthy. |
| Checksum | *44 | | |
| <CR><LF> | | | End of message termination |

Message ID 154: Extended Ephemeris ACK

The SiRFInstantFix software uses Message ID 154 to acknowledge input messages 107, 108 or 110.

```
$PSRF154,110*3B<CR><LF>
```

Table 1-18 contains the parameter definitions and example values.

Table 1-18 Extended Ephemeris ACK

| Name | Example | Unit | Description |
|------------|-----------|------|--|
| Message ID | \$PSRF154 | | PSRF154 protocol header |
| ACK ID | 110 | N/A | Message ID of the message to ACK (107, 108, 110) |
| Checksum | | | |
| <CR> <LF> | | | End of message termination |

Message ID 155: Proprietary

This message is reserved for SiRF extended ephemeris usage only. The content of this message is proprietary.

Table 1-19 contains the message parameter definitions.

Table 1-19 Proprietary

| Name | Example | Unit | Description |
|--------------------|-----------|------|----------------------------|
| Message ID | \$PSRF155 | | PSRF108 protocol header |
| Extended Ephemeris | | | Proprietary message |
| Checksum | | | |
| <CR> <LF> | | | End of message termination |

Message ID 156 (Sub ID 0x20): ECLM ACK/NACK

This is the ACK/NACK response to message ID 114, Sub ID 0x16, 0x17, 0x18, 0x19 or 0x1A. The Sub Message ID for this message is fixed to 0x20.

Table 1-20 contains the values for the following example:

```
$PSRF156,20,72,16,0,0*09<CR><LF>
```

Table 1-20 ECLM ACK/NACK

| Name | Example | Unit | Description |
|----------------|-----------------------|------|---|
| Message ID | \$PSRF156 | | ECLM ACK/NACK |
| Sub ID | 0x20 (Decimal: 32) | | 0x20: Sub ID for ECLM ACK/NACK |
| ACK Message ID | 0x72 | | 114: Msg ID for ECLM Download |
| ACK Sub ID | 0x16 | | 0x16: Sub ID for ECLM Start Download This field can take values 0x16, 0x17, 0x18, 0x19, or 0x1A to ACK corresponding SIDs. |
| ACK/NACK | 0x0 | | 0: ACK 1: NACK |
| Reason | 0x0 | | See Table 1-21 |
| Checksum | *09 | | |
| <CR><LF> | | | End of message termination |

Table 1-21 Description of ACK/NACK Values

| Value | Example | Code | Description |
|-------|---------|---------------------------------|------------------------------------|
| 0 | 0x00 | ECLM_SUCCESS | Success |
| 1 | 0x01 | ECLM_SPACE_UNAVAILABLE | Insufficient space |
| 2 | 0x02 | ECLM_PKT_LEN_INVALID | Packet length field out of range |
| 3 | 0x03 | ECLM_PKT_OUT_OF_SEQ | Packet received is out of sequence |
| 4 | 0x04 | ECLM_DOWNLOAD_SGEE_NONEWFILE | No new file |
| 5 | 0x05 | ECLM_DOWNLOAD_CORRUPTFILE_ERROR | Corrupt file |
| 6 | 0x06 | ECLM_DOWNLOAD_GENERIC_FAILURE | Generic failure |
| 7 | 0x07 | ECLM_API_GENERIC_FAILURE | Generic failure calling CLM API |

Message ID 156 (Sub ID 0x21): ECLM EE Age

This is the response to message ID 114, Sub ID 0x19. The Sub Message ID for this message is fixed to 0x21.

Table 1-22 contains the values for the following example:

```
$PSRF156,21,1,7,2,0,0,0,0,0,2,0,0,0,0,0*10<CR><LF>
```

If NACKed, the reason for the NACK is present in the next byte (see Table 1-21). If ACKed, the following fields appear after the ACK field.

Table 1-22 ECLM EE Age Fields

| Field Name | Description |
|----------------|--|
| numSAT ID | This field indicates the number of times the following fields are present in the message |
| prnNum; | PRN number of satellite for which age is indicated in other fields |
| ephPosFlag | Ephemeris flag to indicate the type of ephemeris available for the satellite: (Position Age): 0: Invalid ephemeris, not available 1: Broadcast Ephemeris (BE) 2: Server-generated EE (SGEE) 3: Client-generated EE (CGEE) |
| eePosAge | Age of EE in 0.01 days (Position Age) |
| cgeePosGPSWeek | GPS week of BE used in the CGEE generation. 0 if ephPosFlag is not set to 3, or set to 0 (Position Age) |
| cgeePosTOE | TOE of BE used in the CGEE generation. 0 if ephPosFlag is not set to 3, or set to 0 (Position Age) |
| ephClkFlag | Ephemeris flag to indicate the type of ephemeris available for the satellite (Clock Age) |
| eeClkAge | Age of EE in 0.01 days (Clock Age) |
| cgeeClkGPSWeek | GPS week of BE used in the CGEE generation. 0 if ephClkFlag is not set to 3, or set to 0 (Clock Age) |
| cgeeClkTOE | TOE of BE used in the CGEE generation; 0 if ephClkFlag is not set to 3 or set to 0 (Clock Age) |

Table 1-23 contains the input values for the following example:

Table 1-23 ECLM EE Age

| Name | Example | Unit | Description |
|----------------|-----------------------|------|--|
| Message ID | \$PSRF156 | | ECLM output |
| Sub ID | 0x21 (Decimal: 33) | | 0x21: Sub ID for ECLM EE Age |
| numSAT | 1 | | This field indicates the number of times the fields repeat |
| prnNum; | 7 | | PRN number = 7 |
| ephPosFlag | 2 | | EE age |
| eePosAge | 00 | | |
| cgeePosGPSWeek | 00 | | |
| cgeePosTOE | 00 | | |
| ephClkFlag | 2 | | |
| eeClkAge | 00 | | |

Table 1-23 ECLM EE Age

| Name | Example | Unit | Description |
|----------------|---------|------|----------------------------|
| cgeeClkGPSWeek | 00 | | |
| cgeeClkTOE | 00 | | |
| Checksum | *10 | | |
| <CR><LF> | | | End of message termination |

Message ID 156 (Sub ID 0x22): ECLM SGEE Age

This is the response to the message ID 114, Sub ID 0x1A. The Sub Message ID for this message is fixed to 0x22.

Table 1-24 contains the input values for the following example:

Sub ID = 0x22, Get EE Age, SGEE Age = 0x7da8, Prediction Interval = 0x15180

Example:

\$PSRF156,22,7da8,15180*3E<CR><LF>

Table 1-24 ECLM Get SGEE Age

| Name | Example | Unit | Description |
|---------------------|-----------------------|------|---|
| Message ID | \$PSRF156 | | ECLM ACK/NACK |
| Sub ID | 0x22 (Decimal: 34) | | 0x22: Sub ID for ECLM Get EE Age ACK/NACK |
| SGEE Age | 0x7da8 | | Age of the satellite |
| Prediction interval | 0x15180 | | Prediction interval |
| Checksum | *3E | | |
| <CR><LF> | | | End of message termination |

Message ID 156 (Sub ID 0x23): ECLM Download Initiate Request

This message is a Download Initiate Request. It is sent if a fresh download of the SGEE file is required.

Table 1-25 contains the input values for the following example:

Sub ID = 0x23, Start Download = 0x1, Time to Wait = 0x0

Example:

\$PSRF156,23,1,0*09<CR><LF>

Table 1-25 contains the message parameter definitions.

Table 1-25 ECLM Download Initiate Request

| Name | Example | Unit | Description |
|----------------|-----------------------|------|---------------------------------|
| Message ID | \$PSRF156 | | ECLM ACK/NACK |
| Sub Message ID | 0x23 (Decimal: 35) | | 0x23: Download Initiate Request |

Table 1-25 ECLM Download Initiate Request

| Name | Example | Unit | Description |
|--------------------|---------|------|---|
| Start/stop | 0x1 | | 1: Start download 0: Stop download |
| Time to Next Start | 0x0 | | 0: Immediate start, otherwise specified number of seconds |
| Checksum | *09 | | Checksum |
| <CR><LF> | | | End of message termination |

Message ID 156 (Sub ID 0x24): ECLM Erase Storage File

This message erases a storage file specified by NVMMID.

Table 1-26 contains the input values for the following example:

Sub Message ID = 0x24, NVM ID = 0x3

Example:

\$PSRF156,24,3*10<CR><LF>

Table 1-26 contains the input values for the following example.

Table 1-26 Erase Storage File

| Name | Example | Unit | Description |
|----------------|-----------------------|------|--|
| Message ID | \$PSRF156 | | ECLM ACK/NACK |
| Sub Message ID | 0x24 (Decimal: 36) | | 0x24: Erase Storage File |
| NVM ID | 0x3 | | 1: Erase SGEE file 2: Erase CGEE file 3: BE file |
| Checksum | *10 | | |
| <CR><LF> | | | End of message termination |

Message ID 156 (Sub ID 0x25): ECLM Update File Content

Send update file content to host for specified file.

Table 1-27 contains the input values for the following example:

Sub ID = 0x25, NVMMID:0x2, Blocks = 0x1

Example:

```
$PSRF156,25,2,11,4f06,1,29,38,c2,75,4e,fb,c,b3,cc,b0,bf,b6,93,3e,84,24,90*1C
<CR><LF>
```

Table 1-27 contains the input values for the following example.

Table 1-27 Update File Content

| Name | Example | Unit | Description |
|----------------|---|------|--|
| Message ID | \$PSRF156 | | ECLM ACK/NACK |
| Sub Message ID | 0x25 (Decimal: 37) | | 0x25: Sub ID for ECLM Update File Content |
| NVM ID | 0x2 | | SGEE File: 1 CGEE File: 2 BE File: 3 |
| Size | 0x11 | | Size |
| Offset | 0x4f06 | | Offset |
| Seq Number | 0x1 | | Seq number |
| Data | 29,38,c2,75,4e,fb,c,b3,cc,b0,bf,b6,93,3e,84,24,90 | | |
| Checksum | *1C | | |
| <CR><LF> | | | End of message termination |

Message ID 156 (Sub ID 0x26): ECLM Request File Content

Request for file content of specified NVM ID.

Table 1-28 contains the input values for the following example.

Sub ID = 0x26, NVMMID:0x3, Blocks = 0x1

Example:

```
$PSRF156,26,3,1,1,4c,0*75<CR><LF>
```

Table 1-28 Request File Content

| Name | Example | Unit | Description |
|----------------|-----------------------|------|--|
| Message ID | \$PSRF156 | | ECLM ACK/NACK |
| Sub Message ID | 0x26 (Decimal: 38) | | 0x26: Sub ID for ECLM Request for file content |
| NVM ID | 0x3 | | SGEE File: 1 CGEE File: 2 BE File: 3 |
| Seq Number | 0x1 | | |
| Num Blocks | 0x1 | | Number of blocks in packet |

Table 1-28 Request File Content

| Name | Example | Unit | Description |
|--------------|---------|------|----------------------------|
| Block Size | 0x4c | | |
| Block offset | 0x0 | | Offset in file |
| Checksum | *75 | | |
| <CR><LF> | | | End of message termination |

Message ID 160: Watchdog Timeout and Exception Condition

This message notifies a PVT product host of a watchdog timeout or processor exception in the receiver. The consistent accumulation of these notification messages by the host can produce statistics for:

- Reliability measurement and analysis
- For troubleshooting purposes

For the GSD4e, it has the critical purpose of enabling the host to determine the need for reloading the patch RAM. The watchdog event, and some exception events, are indications of potential corruption in the patch RAM. This message enables the host to initiate the patch download protocol.

Typically, upon receipt of this message, the host requests to switch the receiver into binary OSP messaging mode. Already in OSP messaging mode, the host polls the software version of the receiver, and the response contains the actual patch status of the receiver. The host then compares this status with the last applied patch according to the patch maintenance value stored in the host. If the software version response does not indicate the up-to-date patch status, the host initiates the reload of the required patch according to the latest patch maintenance value stored in the host. After completing the patch procedure using the binary OSP messages, the host switches back to NMEA mode for normal operation to continue.

Example:

```
$PSRF160,W,1,0*5A<CR><LF>
```

This message is not supported in the GSD4t or earlier products.

Table 1-29 Watchdog and Exception Condition Notification

| Name | Example | Unit | Description |
|----------------------|-----------|------|---|
| Message ID | \$PSRF160 | | PSRF160 protocol header |
| Event condition | W | | W: Watchdog time-out event E: Reserved: Exception condition event |
| Patch RAM corruption | 1 | | 0: Intact, not corrupted 1: Corrupted, need to restore |
| Exception code | - | | Hexadecimal value of the processor exception code register (0 if event 'W') |
| Checksum | *hh | | |
| <CR><LF> | | | End of message termination |

Message ID 225: Reserved

Except for Sub ID 6, the contents of this message are proprietary, reserved for use by SiRF engineers, and are not described here.

Input Messages



This section describes the NMEA input messages listed in Table 2-1.

Table 2-1 NMEA Input Messages

| Message | Description |
|----------|---|
| 100 | SetSerialPort: Set Port A parameters and protocols |
| 101 | NavInit: Parameters required to start using X/Y/Z ¹ |
| 102 | SetDGPSPort: Set port B parameters for DGPS input |
| 103 | Query NMEA Message and/or set output rate |
| 104 | LLANavInit: Parameters to Start Using Lat/Long/Alt ² |
| 105 | DevDataOn/Off: Development Data Messages On/Off |
| 106 | Selection of Datum for Coordinate Transformation |
| 107 | Extended ephemeris proprietary message |
| 108 | Extended ephemeris proprietary message |
| 110 | Extended ephemeris debug |
| 114,0x16 | ECLM start download |
| 114,0x17 | ECLM file size |
| 114,0x18 | ECLM packet data |
| 114,0x19 | ECLM Get EE Age |
| 114,0x1A | ECLM Get SGEE Age |
| 114,0x1B | ECLM Host File Content |
| 114,0x1C | ECLM Host ACK/NACK |
| 117 | System Turn Off |
| 120 | Storage Configuration Setting |
| 200 | Marketing Software Configuration |
| MSK | Command message to an MSK radio-beacon receiver |

1. Input coordinates must be WGS84.

Note – NMEA input messages 100 to 200 are SiRF proprietary NMEA messages. The MSK NMEA string is as defined by the NMEA 0183 standard.

Table 2-2 shows which SiRF platforms support the NMEA input messages.

Table 2-2 Supported NMEA Input Messages

| Message | GSW2 | SiRFDriVe | SiRFXTrac | SiRFLoc | GSW3 & GSWLT3 | SiRFDIRect | GSD3fw | GSD3fLP | Code Linked Host | | GPIO Strapped Chip | | OSP NMEA Switch Msg | |
|----------|------------------|-----------|------------------|---------|------------------|------------------|--------|---------|------------------|-------|--------------------|-------|---------------------|-------|
| | | | | | | | | | GSD4t | GSD4e | GSD4t | GSD4e | GSD4t | GSD4e |
| 100 | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 101 | Yes | Yes | Yes ¹ | Yes | Yes ¹ | Yes ¹ | Yes | Yes | No | No | No | Yes | No | Yes |
| 102 | Yes | Yes | No | No | Yes | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 103 | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 104 | Yes | Yes | Yes ¹ | Yes | Yes ¹ | Yes ¹ | Yes | Yes | No | No | No | Yes | No | Yes |
| 105 | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 106 | Yes | Yes | Yes | Yes | Yes | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 107 | 2.5 and later | No | 2.3 and later | No | Yes | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 108 | 2.5 and later | No | 2.3 and later | No | Yes | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 110 | 2.5 and later | No | 2.3 and later | No | 3.2.0 and later | Yes | Yes | Yes | No | No | No | Yes | No | Yes |
| 114,0x16 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 114,0x17 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 114,0x18 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 114,0x19 | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 114,0x1A | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 114,0x1B | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 114,0x1C | No | No | No | No | No | No | No | Yes | Yes | Yes | No | Yes | No | Yes |
| 117 | No | No | No | No | No | No | No | No | Yes | Yes | Yes | Yes | Yes | Yes |
| 120 | No | No | No | No | No | No | No | No | No | Yes | No | Yes | No | Yes |
| 200 | Yes ² | No | No | No | No | No | No | No | No | No | No | No | No | No |
| MSK | Yes | Yes | No | No | No | No | No | No | No | No | No | No | No | No |

1. In GSW firmware versions prior to GSW3.5.0, input of position and [XXXtme] time are not allowed.

2. Only with a GSC2xr chip.

Message ID 100: SetSerialPort

This command message is used to set the protocol (SiRF binary or NMEA) and/or the communication parameters (Baud rate, data bits, stop bits, and parity). Generally, this command is used to switch the module back to SiRF binary protocol mode where a more extensive command message set is available. When a valid message is received, the parameters are stored in battery-backed SRAM and the receiver resumes, after a reset, using the saved parameters.

Table 2-3 contains the input values for the following example:

Switch to SiRF binary protocol at 9600,8,N,1
 \$PSRF100,0,9600,8,1,0*0C<CR><LF>

Table 2-3 Set Serial Port Data Format

| Name | Example | Unit | Description |
|------------|-----------|------|--|
| Message ID | \$PSRF100 | | PSRF100 protocol header |
| Protocol | 0 | | 0=SiRF binary 1=NMEA |
| Baud | 9600 | | 1200, 2400, 4800, 9600, 19200, 38400, 57600, or 115200 |
| DataBits | 8 | | 8 only |
| StopBits | 1 | | 1 only |
| Parity | 0 | | 0=None only |
| Checksum | *0C | | |
| <CR> <LF> | | | End of message termination |

For the GSD4e, operation at speeds below 38400 carries risk of dropped messages when using SGEE (Server Generated Extended Ephemeris).

Message ID 101: NavigationInitialization

This command restarts the receiver, and specifies the type of restart. Optionally, it may also initialize position (in X, Y, Z ECEF coordinates), clock drift, GPS Time Of Week and GPS Week Number. This enables the receiver to search for the correct satellite signals at the correct signal parameters. Correct initialization parameters enable the receiver to quickly acquire signals.

For software that does not support initializing data (some versions of GSW3 and GSWLT3, and SiRFXTrac), attempting to include initializing data may cause unpredictable results. Do not set the initialize-data bit in the ResetCfg word.

Table 2-4 contains the input values for the following example:

Start using known position and time.

```
$PSRF101,-2686700,-4304200,3851624,96000,497260,921,12,3*1C<CR><LF>
```

Table 2-4 Navigation Initialization Data Format

| Name | Example | Unit | Description |
|--------------|-----------|--------|--|
| Message ID | \$PSRF101 | | PSRF101 protocol header |
| ECEF X | -2686700 | meters | X coordinate position |
| ECEF Y | -4304200 | meters | Y coordinate position |
| ECEF Z | 3851624 | meters | Z coordinate position |
| ClkDrift | 96000 | Hz | Clock Drift of the Receiver ¹ |
| TimeOfWeek | 497260 | sec | GPS Time Of Week |
| WeekNo | 921 | | GPS Week Number |
| ChannelCount | 12 | | Range 1 to 12 |
| ResetCfg | 3 | | See Table 2-5 and Table 2-6 |
| Checksum | *1C | | |
| <CR><LF> | | | End of message termination |

1. Use 0 for last saved value if available. If this is unavailable, a default value of 96250 is used.

Table 2-5 Reset Mode Value (SiRFstarIII and Later)

| Value | Description |
|-------|------------------------|
| 1 | Hot start |
| 2 | Warm start (no init) |
| 3 | Warm start (with init) |
| 4 | Cold start |
| 8 | Factory start |

Table 2-6 Reset Configuration: SiRFLoc Specific

| Decimal | Description |
|---------|--|
| 00 | Perform a hot start using internal RAM data. No initialization data is used. |
| 01 | Use initialization data and begin in start mode. Uncertainties are 5 seconds time accuracy and 300 km position accuracy. Ephemeris data in SRAM is used. |
| 02 | No initialization data is used, ephemeris data is cleared, and warm start performed using remaining data in RAM. |
| 03 | Initialization data is used, ephemeris data is cleared, and warm start performed using remaining data in RAM. |
| 04 | No initialization data is used. Position, time, and ephemeris are cleared, and a cold start is performed. |
| 08 | No initialization data is used. Internal RAM is cleared and a factory reset is performed. |

Message ID 102: SetDGPSPort

This command is used to control the serial port used to receive RTCM differential corrections. Differential receivers may output corrections using different communication parameters. If a DGPS receiver is used that has different communication parameters, use this command to allow the receiver to correctly decode the data. When a valid message is received, the parameters are stored in battery-backed SRAM and the receiver restarts using the saved parameters.

Note – In receivers that do not support RTCM 104 DGPS (e.g. SiRFStarIII), this command is not supported.

Table 2-7 contains the input values for the following example:

Set DGPS Port to 9600 baud, 8 data bits, 1 stop bit, no parity bit.

```
$PSRF102,9600,8,1,0*12<CR><LF>
```

Table 2-7 Set DGPS Port Data Format

| Name | Example | Unit | Description |
|------------|-----------|------|--|
| Message ID | \$PSRF102 | | PSRF102 protocol header |
| Baud | 9600 | | 1200, 2400, 4800, 9600, 19200, 38400, 57600, or 115200 |
| DataBits | 8 | | 8,7 |
| StopBits | 1 | | 0,1 |
| Parity | 0 | | 0=None 1=Odd 2=Even |
| Checksum | *12 | | |
| <CR><LF> | | | End of message termination |

Message ID 103: Query/Rate Control

This command is used to control the output of only standard NMEA messages GGA, GLL, GSA, GSV, RMC, and VTG. It also controls the ZDA message in software that supports it. Using this command message, standard NMEA messages may be polled once, or setup for periodic output. Checksums may also be enabled or disabled depending on the needs of the receiving program. NMEA message settings are saved in battery-backed memory for each entry when the message is accepted.

Table 2-8 contains the input values for the following example:

Query the GGA message with checksum enabled

```
$PSRF103,00,01,00,01*25<CR><LF>
```

Table 2-8 Query/Rate Control Data Format

| Name | Example | Unit | Description |
|-------------|-----------|------|---|
| Message ID | \$PSRF103 | | PSRF103 protocol header |
| Msg | 00 | | Message to control. See Table 2-9. ¹ |
| Mode | 01 | | 0 = Set Rate 1 = Query one time 2 = ABP On 3 = ABP Off |
| Rate | 00 | sec | Output Rate, 0 = Off 1–255 = seconds between messages ² |
| CksumEnable | 01 | | 0=Disable Checksum 1=Enable Checksum |
| Checksum | *25 | | |
| <CR><LF> | | | End of message termination |

1. The Msg field is ignored if the Mode field has values of 2 or 3 (ABP On/Off).

2. The Rate field is ignored unless the Mode field is set to 0 (Set Rate).

Table 2-9 Messages

| Value | Description |
|-------|---------------------------------------|
| 0 | GGA |
| 1 | GLL |
| 2 | GSA |
| 3 | GSV |
| 4 | RMC |
| 5 | VTG |
| 6 | MSS (If internal beacon is supported) |
| 7 | Not defined |
| 8 | ZDA (if 1PPS output is supported) |
| 9 | Not defined |

Note – In TricklePower mode, the update rate specifies TricklePower cycles rather than seconds. If the TP cycle is set at 5 seconds, then an update rate of 2 means to output the message every 2 cycles, or 10 seconds.

Message ID 104: LLANavigationInitialization

This command is used to cause a restart of the receiver, and to specify the type of restart. Optionally, it may also initialize position (in latitude, longitude, and altitude), clock drift, GPS Time Of Week and GPS Week Number. This enables the receiver to search for the correct satellite signals at the correct signal parameters. Correct initialization parameters enable the receiver to quickly acquire signals.

For software that does not support initializing data (GSW3, GSWLT3, SiRFXTac), attempting to include initializing data may cause unpredictable results. Do not set the initialize-data bit in the ResetCfg word.

Table 2-10 contains the input values for the following example:

Start using known position and time.

```
$PSRF104,37.3875111,-121.97232,0,96000,237759,1946,12,1*07<CR><LF>
```

Table 2-10 LLA Navigation Initialization Data Format

| Name | Example | Unit | Description |
|--------------|------------|---------|--|
| Message ID | \$PSRF104 | | PSRF104 protocol header |
| Lat | 37.3875111 | degrees | Latitude + = North (Range 90 to -90) |
| Lon | -121.97232 | degrees | Longitude + = East (Range 180 to -180) |
| Alt | 0 | meters | Altitude position |
| ClkDrift | 96000 | Hz | Clock Drift of the Receiver ¹ |
| TimeOfWeek | 237759 | sec | GPS Time Of Week |
| WeekNo | 1946 | | Extended GPS Week Number |
| ChannelCount | 12 | | Range 1 to 12 |
| ResetCfg | 1 | | See Table 2-11 |
| Checksum | *07 | | |
| <CR><LF> | | | End of message termination |

1. Use 0 for last saved value if available. If this is unavailable, a default value of 96,250 Hz is used.

Table 2-11 Reset Mode Value (SiRFstarIII and Later)

| Value | Description |
|-------|------------------------|
| 1 | Hot start |
| 2 | Warm start (no init) |
| 3 | Warm start (with init) |
| 4 | Cold start |
| 8 | Factory start |

Message ID 105: Development Data On/Off

This command turns development data (debug messages) on and off. Development data can be used to help diagnose system problems since many parts of the software contain messages that are output when problems are detected.

Table 2-12 contains the input values for the following example:

```
$PSRF105,1*3E<CR><LF>
```

Table 2-12 Development Data On/Off Data Format

| Name | Example | Unit | Description |
|------------|-----------|------|----------------------------|
| Message ID | \$PSRF105 | | PSRF105 protocol header |
| Debug | 1 | | 0=Off 1=On |
| Checksum | *3E | | |
| <CR><LF> | | | End of message termination |

Message ID 106: Select Datum

This message allows the selection of an alternate map datum. The receiver software may contain one or more alternate datums in addition to WGS84, the default GPS datum. The table below lists some datums that may be in a particular software build. In addition, other datums may have been added by either SiRF or by developers with SDK software access. Available datums, if different from the list below, should be documented in the system or software documentation.

Table 2-13 contains the input values for the following examples:

1. Datum select TOKYO_MEAN

```
$PSRF106,178*32<CR><LF>
```

Table 2-13 Select Datum Data Format

| Name | Example | Unit | Description |
|------------|-----------|------|---|
| Message ID | \$PSRF106 | | PSRF106 protocol header |
| Datum | 178 | | 21=WGS84 178=TOKYO_MEAN 179=TOKYO_JAPAN 180=TOKYO_KOREA 181=TOKYO_OKINAWA |
| Checksum | *32 | | |
| <CR><LF> | | | End of message termination |

Message ID 107: Proprietary

This message is reserved for SiRFInstantFix usage only. The content of this message is proprietary.

Table 2-14 contains the message parameter definitions.

Table 2-14 Proprietary

| Name | Example | Unit | Description |
|--------------------|-----------|------|----------------------------|
| Message ID | \$PSRF107 | | PSRF107 protocol header |
| Extended Ephemeris | | | Proprietary message |
| Checksum | | | |
| <CR><LF> | | | End of message termination |

Message ID 108: Proprietary

This message is reserved for SiRFInstantFix usage only. The content of this message is proprietary.

Table 2-15 contains the message parameter definitions.

Table 2-15 Proprietary

| Name | Example | Unit | Description |
|--------------------|-----------|------|----------------------------|
| Message ID | \$PSRF108 | | PSRF108 protocol header |
| Extended Ephemeris | | | Proprietary message |
| Checksum | | | |
| <CR><LF> | | | End of message termination |

Message ID 110: Extended Ephemeris Debug

This message allows control of a SiRFInstantFix debug flag. Turning on the flag forces the receiver to ignore broadcast ephemeris from the satellites and only use SiRFInstantFix ephemeris for navigation.

Table 2-16 contains the message parameter definitions.

Table 2-16 Extended Ephemeris Debug

| Name | Example | Unit | Description |
|------------|------------|------|---|
| Message ID | \$PSRF110 | | PSRF110 protocol header |
| DEBUG_FLAG | 0x01000000 | | 0x01000000 = Debug flag on, ignore broadcast ephemeris 0x00000000 = Debug flag off, normal operation |
| Checksum | | | |
| <CR><LF> | | | End of message termination |

Message ID 112: Set Message Rate

This message is intended only for SiRFInstantFix and must not be used otherwise.

Table 2-17 contains the message parameter definitions for the following example:

```
$PSRF112,140,1,1*3B<CR><LF>
```

Table 2-17 Table Set Message Rate

| Name | Example | Unit | Description |
|-------------------|---------|------|--|
| Message ID | PSRF112 | | PSRF112 protocol header |
| Message ID to set | 140 | | This is the only NMEA message ID supported |
| Message rate | 1 | sec | 140 – valid rate is 1 (i.e. occurring once at every periodic EE event, in every 6 seconds) or 0 (to disable) |
| Send Now | 1 | | Poll NMEA message ID once. |

Message ID 113 (Sub ID 0x01): Set GRF3i+ IF Bandwidth Mode

This message enables the user to set the IF bandwidth mode for the GRF3i+.

Table 2-18 contains the values for the following example:

Sub ID = 0x1, GRF3i+ Bandwidth Mode Selection = 0x1,

Example:

```
$PSRF113,01,01*24<CR><LF>
```

Table 2-18 Set GRF3i+ IF Bandwidth Mode

| Name | Example | Unit | Description |
|------------------------------------|-----------------------|------|--|
| Message ID | \$PSRF113 | | GRF3i+ protocol header |
| Sub ID | 0x01 (Decimal: 01) | | 0x01 : Set GRF3i+ IF bandwidth mode |
| GRF3i+ IF Bandwidth Mode Selection | 0x01 | | 0 = Wideband Mode 1 = Narrowband Mode [default] |
| Checksum | *24 | | |
| <CR><LF> | | | End of message termination. |

Message ID 113 (Sub ID 0x02): Set GRF3i+ Normal/Low Power RF Mode

This message enables the user to set the RF power mode to normal or low.

Table 2-19 contains the values for the following example:

Sub ID = 0x2, GRF3i+ power mode =0x1

Example:

```
$PSRF113,02,01*27<CR><LF>
```

Table 2-19 Set GRF3i+ IF Bandwidth Mode

| Name | Example | Unit | Description |
|-----------------------------|-----------------------|------|---|
| Message ID | \$PSRF113 | | GRF3i+ protocol header |
| Sub ID | 0x02 (Decimal: 02) | | 0x02 : Set GRF3i+ power mode |
| GRF3i+ power mode Selection | 0x01 | | 0 = Normal power [default] 1 = Low power |
| Checksum | *27 | | |
| <CR><LF> | | | End of message termination. |

Note – GRF3i+ Power Mode would be internally saved to NVM. By default, it would be initialized to 0 (Normal power).

Message ID 114 (Sub ID 0x16): ECLM Start Download

This message indicates to the GPS receiver that Host EE Downloader wants to initiate the SGEE file download. The Sub Message ID for this message is fixed to 0x16.

Table 2-20 contains the input values for the following example:

Sub ID = 0x16

Example:

```
$PSRF114,16*08<CR><LF>
```

Table 2-20 ECLM Start Download

| Name | Example | Unit | Description |
|------------|-----------------------|------|--------------------------------------|
| Message ID | \$PSRF114 | | ECLM Download Packet Header |
| Sub ID | 0x16 (Decimal: 22) | | 0x16: Sub ID for ECLM Start Download |
| Checksum | *08 | | |
| <CR><LF> | | | End of message termination |

The receiver reports the success or failure of this message with message ID 156, Sub ID 0x20.

Message ID 114 (Sub ID 0x17): ECLM File Size

This message is sent from Host EE Downloader to the GPS receiver to indicate the size of the SGEE file to be downloaded. The Sub Message ID for this message is fixed to 0x17.

Table 2-21 contains the values for the following example:

Sub Message ID = 0x17, SGEE File Size = 0x2859

Example:

```
$PSRF114,17,2859*23<CR><LF>
```

Table 2-21 ECLM File Size

| Name | Example | Unit | Description |
|-------------|-----------------------|------|----------------------------|
| Message ID | \$PSRF114 | | Message ID |
| Sub ID | 0x17 (Decimal: 23) | | 0x17: SGEE File Length |
| File length | 0x2859 | | File length |
| Checksum | *23 | | |
| <CR><LF> | | | End of message termination |

The receiver reports the success or failure of this message with message ID 156, Sub ID 0x20.

Message ID 114 (Sub ID 0x18): ECLM Packet Data

This message is sent from Host EE Downloader to the GPS receiver to indicate the size of the SGEE file to be downloaded. The Sub Message ID for this message is fixed to 0x18.

Table 2-22 contains the values for the following example:

Sub ID = 0x18, Packet Sequence No = 1, Packet Length = 32

Example:

```
$PSRF114,18,1,32,62,12,31,6,3,2,7,d9,7,7,0,0,39,6d,8f,12,0,0,0,0,0,0,1,2d,9a,e7,5,2,ff,fe,28,5*3D<CR><LF>
```

Table 2-22 SGEE Packet Data

| Name | Example | Unit | Description |
|--------------------|---|------------|---|
| Message ID | \$PSRF114 | | Message ID |
| Sub ID | 0x18 (Decimal: 24) | | 0x18: SGEE Packet Data |
| Packet Sequence No | 1 | In decimal | File length |
| Packet Length | 32 | In decimal | Length of this packet |
| Packet Data | 62,12,31,6,3,2,7,d9,7,7,0,0,39,6d,8f,12,0,0,0,0,0,0,1,2d,9a,e7,5,2,ff,fe,28,5 | | SGEE data in this packet of length PacketLength |
| Checksum | *3D | | |
| <CR><LF> | | | End of message termination |

The receiver reports the success or failure of this message with message ID 156, Sub ID 0x20.

Message ID 114 (Sub ID 0x19): ECLM Get EE Age

This message is sent from Host EE Downloader to the GPS receiver to get the EE age from the GPS receiver. The Sub Message ID for this message is fixed to 0x19.

Table 2-23 contains the values for the following example:

Sub ID = 0x19, Num Sat = 1, Prn Num = 1

Example:

\$PSRF114,19,1,1,0,0,0,0,0,0,0,0,0,0,0,0*1B<CR><LF>

Table 2-23 ECLM Get EE Age

| Name | Example | Unit | Description |
|----------------|-----------------------|------|---|
| Message ID | \$PSRF114 | | Message ID |
| Sub ID | 0x19 (Decimal: 25) | | 0x19: Get EE Age |
| Num Sat | 0x1 | | Number of times below fields will be repeated |
| prnNum | 0x1 | | PRN number = 1 |
| ephPosFlag | 0x0 | | |
| eePosAge | 0x0 | | |
| cgeePosGPSWeek | 0x0 | | |
| cgeePosTOE | 0x0 | | |
| ephClkFlag | 0x0 | | |
| eeClkAge | 0x0 | | |
| cgeeClkGPSWeek | 0x0 | | |
| cgeeClkTOE | 0x0 | | |
| Pad | 0x0 | | |
| Checksum | *1B | | |
| <CR><LF> | | | End of message termination |

The receiver reports the success or failure of this message with message ID 156, Sub ID 0x21 or 0x20.

Message ID 114 (Sub ID 0x1A): ECLM Get SGEE Age

This message is sent from Host EE Downloader to the GPS receiver to get the SGEE age from the GPS receiver. The Sub Message ID for this message is fixed to 0x1A.

Table 2-24 contains the values for the following example:

Sub ID = 0x1A, Sat ID = 1

Example:

\$PSRF114,1a,1*42<CR><LF>

Table 2-24 Get SGEE Age

| Name | Example | Unit | Description |
|------------|--------------------|------|--|
| Message ID | \$PSRF114 | | Message ID |
| Sub ID | 0x1A (Decimal: 26) | | 0x1A: Get SGEE Age |
| Sat ID | 0x1 | | Satellite ID for which SGEE Age is asked |
| Checksum | *42 | | |
| <CR><LF> | | | End of message termination |

The receiver reports the success or failure of this message with message ID 156, Sub ID 0x22 (success) or 0x20 (failure).

Message ID 114 (Sub ID 0x1B): ECLM Host File Content

This message is sent to the GPS receiver in response to a Request File Content message. The Sub Message ID for this message is fixed to 0x1B.

Table 2-25 contains the values for the following example:

Sub Message ID = 0x1B, NVM ID = 3, Num Blocks = 1

Example:

\$PSRF114,1b,1,3,1,a,0,0,0,f,6,0,f0,0,0,4a,0*41<CR><LF>

Table 2-25 Host File Content

| Name | Example | Unit | Description |
|--------------|-----------------------|------|--|
| Message ID | \$PSRF114 | | Message ID |
| Sub ID | 0x1B (Decimal: 27) | | 0x1B: Host File Content |
| SeqNum | 0x01 | | |
| NVM ID | 0x03 | | 1: SGEE file 2: CGEE file 3: BE file |
| Num Blocks | 0x1 | | Number of blocks per packet |
| Block Length | 0xA | | Block size |
| Offset | 0x0 | | Offset of block in file |
| Data | 0,0,f,6,0,f0,0,0,4a,0 | | Block data |
| Checksum | *41 | | |
| <CR><LF> | | | End of message termination |

Message ID 114 (Sub ID 0x1C): ECLM Host ACK/NACK

This message is the response to Output Message 156 with SubMsgID 0x23, 0x24 or 0x25.

Table 2-26 contains the values for the following example:

ACK for Downloader initiate request
 \$PSRF114,1c,9c,23,0,0*06<CR><LF>

Table 2-26 Host ACK/NACK

| Name | Example | Unit | Description |
|----------------|-----------------------|------|---|
| Message ID | \$PSRF114 | | Message ID |
| Sub ID | 0x1C (Decimal: 28) | | 0x1C: Host ACK/NACK |
| ACK Message ID | 0x9C | | \$PSRF156 |
| ACK Sub ID | 0x23 | | This can contain values 0x23, 0x24, 0x25 |
| ACK/NACK | 0x0 | | 0x0: ACK 0x1: NACK |
| Reason | 0x0 | | 0x0: SUCCESS 0x1: Invalid NVMID 0x13: File access error |
| Checksum | *06 | | |
| <CR><LF> | | | End of message termination |

Message ID 117: System Turn Off

This message requests that the GPS receiver perform an orderly shutdown and switch to hibernate mode.

Table 2-27 contains the values for the following example:

\$PSRF117,16*0B<CR><LF>

Table 2-27 System Turn Off

| Name | Example | Unit | Description |
|------------|-----------------------|------|----------------------------|
| Message ID | \$PSRF117 | | Message ID |
| Sub ID | 0x10 (Decimal: 16) | | 0x10: System turn off |
| Checksum | *0B | | |
| <CR><LF> | | | End of message termination |

Message ID 120: Storage Config Setting

This command sets storage configuration options to determine on which storage media the different types of system data will be physically stored.

Table 2-27 contains the input values for the following example:

Store patches on I2Cserial flash and extended ephemeris data on I²C EEROM.

```
$PSRF120,F,R,*<checksum><CR><LF>
```

Table 2-28 Storage Configuration Option Settings Format

| Name | Example | Unit | Description |
|-----------------------|-----------|------|---|
| Message ID | \$PSRF120 | | PSRF120 Protocol Header |
| Patch Storage Setting | F | | “N” = Do not store to I ² C serial flash (default) “F” = Store to I ² C serial flash “0” = No change applied to patch |
| | R | | “H” = Storage available on host “R” = I ² C EEROM provided for GSD4e access (default) “F” = Store to parallel FLASH “N” = No storage “0” = No change applied to patch storage settings |
| CheckSum | *... | | |
| <CR><LF> | | | End of message termination |

Note – This message is supported by GSD4e and later.

Message ID 200: Marketing Software Configuration

Note – This message is used to select one of the pre-programmed configurations within ROM-based devices. Refer to the appropriate product datasheet to determine message format and specific configurations supported.

Message ID MSK: MSK Receiver Interface

Table 2-29 contains the values for the following example:

```
$GPMSK,318.0,A,100,M,2,*45<CR><LF>
```

Table 2-29 MSK Data Format

| Name | Example | Unit | Description |
|---|---------|------|------------------------------------|
| Message ID | \$GPMSK | | MSK protocol header |
| Beacon Frequency | 318.0 | kHz | Frequency to use |
| Auto/Manual Frequency ¹ | A | | A : Auto M : Manual |
| Beacon Bit Rate | 100 | | Bits per second |
| Auto/Manual Bit Rate ² | M | | A : Auto M : Manual |
| Interval for Sending \$--MSS ³ | 2 | sec | Sending of MSS messages for status |

1. If Auto is specified, the previous field is ignored and the receiver will search for beacon frequency automatically.
2. If Auto is specified, the previous field is ignored and the receiver will search for the correct bit rate.
3. When status data is not to be transmitted this field is null.

Note – The NMEA messages supported by the receiver does not provide the ability to change the DGPS source. If you need to change the DGPS source to internal beacon, use the SiRF binary protocol and then switch to NMEA.



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